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Controllability and
Observability - Problem 1 -

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State Space Analysis - Control Systems

Basic Control Actions

What is Control Engineering?

~~Modern Control System~~

~~Transfer Functions Part 2~~

Modern Control System

Transfer Functions Part 1

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**Control Systems Lectures -
Transfer Functions** *Hardware
Demo of a Digital PID
Controller*

**Proportional-Integral
Controller: Reducing the
steady state error using a
PI controller, 1/12/2014**

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????) LQR ?? ???

Matlab/simulink ?? ?? ??

optimal control ????? ?????!

Hamilton-Jacobi equation !

What is the use of PI
controller in control
systems

Intro to Control - 6.3 State-

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Space Model to Transfer
Function

Intro to Control - 11.1

Steady State Error (with
Proportional Control)

Example: Design PID

Controller Simple Examples
of PID Control

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A Simple Feedback Control
Example System Dynamics and
Control: Module 4b -
Modeling Mechanical Systems
Examples Books for reference
- Electrical Engineering
Mathematical Models of
Dynamic Systems 1.1

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Introduction to Control
Systems/Engineering MIT
Feedback Control Systems
Modern Control System
Transfer Functions Part 3
Modern Control Systems -
Mass spring damper example
Modern Control Engineering

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approach, root-locus
approach, and state-space
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The text provides a gradual
development of control
theory, shows how to solve
all computational problems

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with MATLAB, and avoids
highly mathematical
arguments.

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Professor of engineering who was born in Tokyo, Japan ; on January 6 of 1925. He earned a Bachelor degree in Mechanical Engineering from the University of Tokyo in 1947.

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Katsuhiko Ogata (Author of Modern Control Engineering)

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This edition of Modern Control Engineering is organized into ten chapters. The outline of this book is as follows: Chapter 1 presents an introduction to control systems. ...

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Katsuhiko Ogata x Preface. 1
Introduction to Control
Systems 1-1 INTRODUCTION
Control theories commonly
used today are classical
control theory (also called
con-

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coverage of control
engineering, including
frequency response approach,
root-locus approach, and
state-space approach to
analysis and design of
control systems.

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approach to analysis and design of control systems. The text provides a gradual development of control theory, shows how to solve all computational problems with MATLAB, and avoids highly mathematical

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arguments.

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